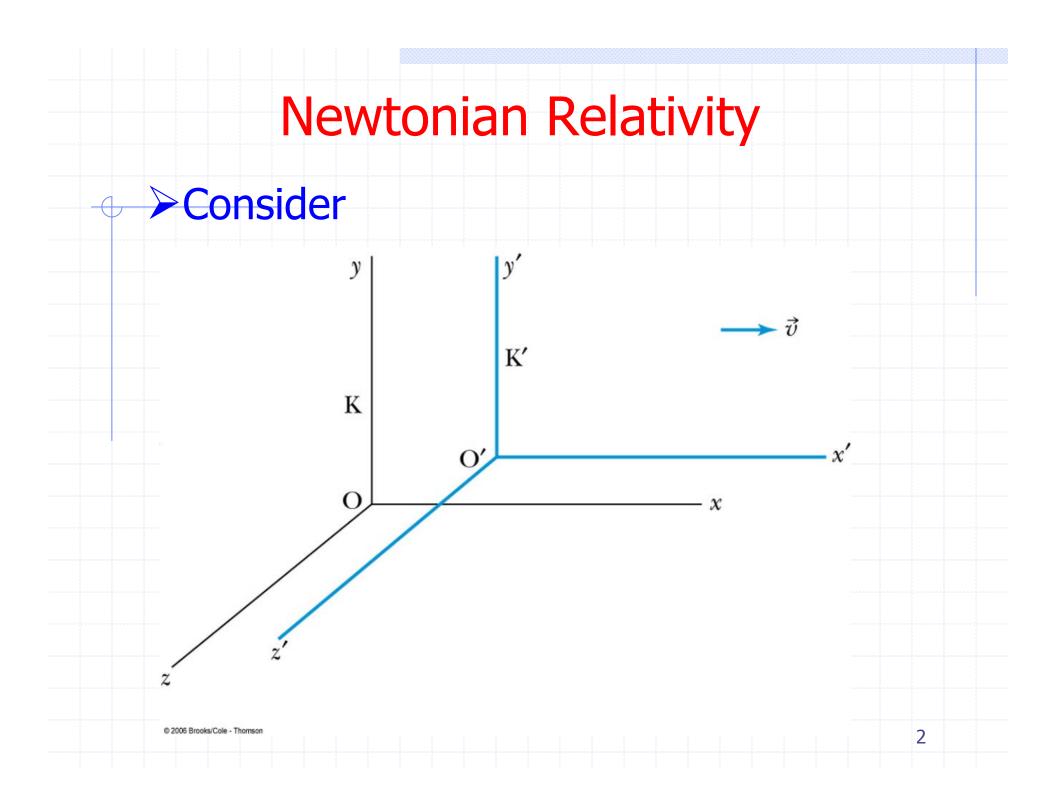
Newtonian Relativity

A reference frame in which Newton's laws are valid is called an inertial frame
Newtonian principle of relativity or Galilean invariance
If Newton's laws are valid in one reference frame, then they are also valid in a reference frame moving at uniform velocity

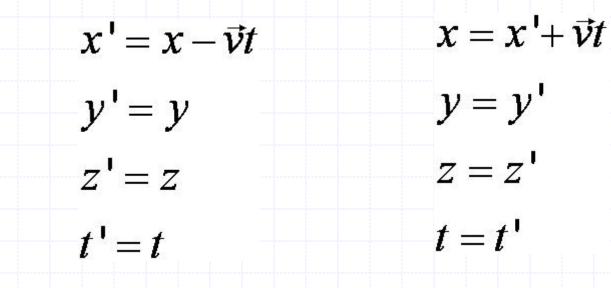
relative to the first system

Thus this moving frame is also an inertial frame



Newtonian Relativity

→ Galilean transformation

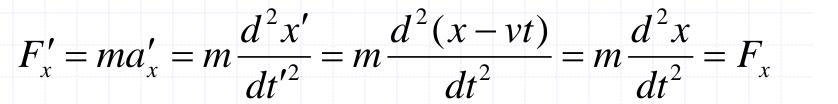


Note time is the same in both systems

Newtonian Relativity

- Note Newton's laws are valid in both frames
 - The force and acceleration are the same in both frames
 - There is no way to detect which frame is moving and which is at rest

$$F'_{y} = ma'_{y} = m\frac{d^{2}y'}{dt'^{2}} = m\frac{d^{2}y}{dt^{2}} = ma_{y} = F_{y}$$

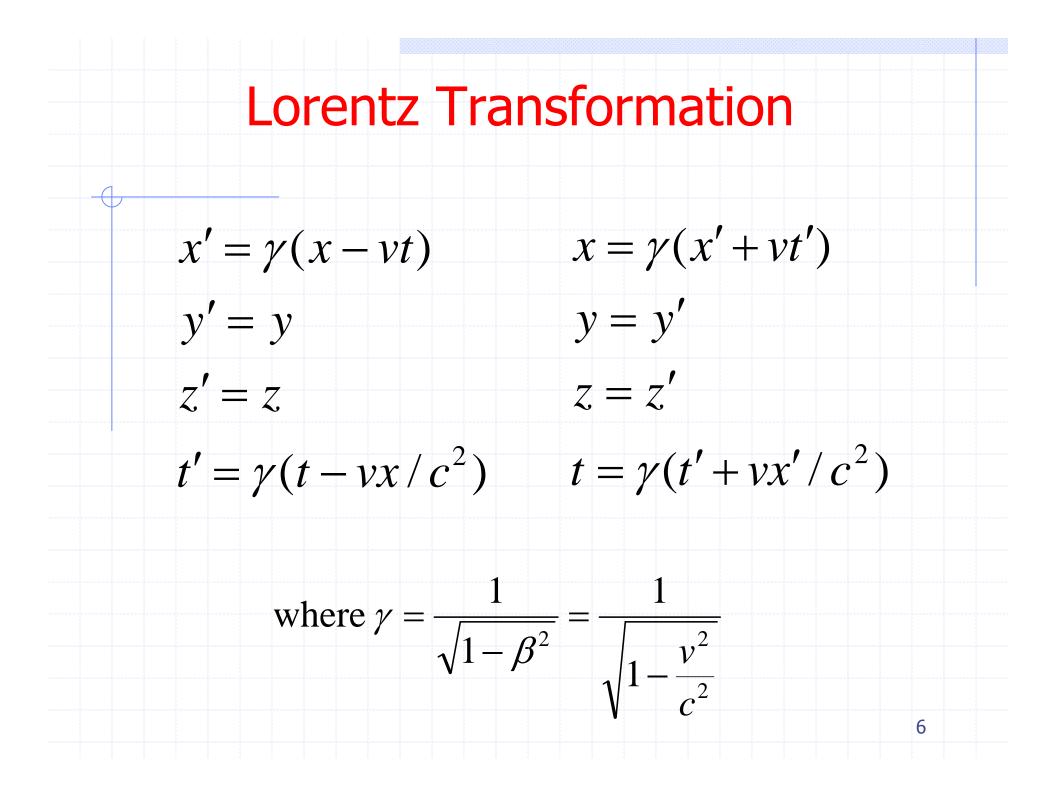


We immediately see the Galilean transformation is inconsistent with Einstein's postulates

• If the velocity of light = c in frame K, the velocity of light = c - V in frame K'

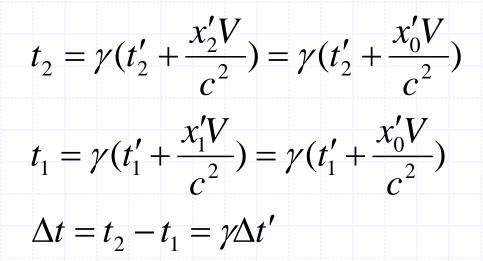
The Lorentz transformation satisfies Einstein's postulates and also reduces to the Galilean transformation at low velocities

A derivation is given in Thornton and Rex p30-31



Time dilation revisited

• Let $\Delta t' = t_2' - t_1'$ be the proper time interval measured by a clock fixed at x_0' in K'



The clocks in S read a time longer than the proper time. The moving clock in S' runs slow.

Length contraction revisited

• Consider a measuring rod with proper length $\Delta x' = x_2' - x_1'$. The interval Δx as viewed in S must have the positions measured at the same time t_0 in S.

$$x_{2}' = \gamma(x_{2} - Vt_{2}) = \gamma(x_{2} - Vt_{0})$$
$$x_{1}' = \gamma(x_{1} - Vt_{1}) = \gamma(x_{1} - Vt_{0})$$
$$\Delta x = \Delta x' / \gamma$$

The length of the moving object as measured in S is shorter than the proper length

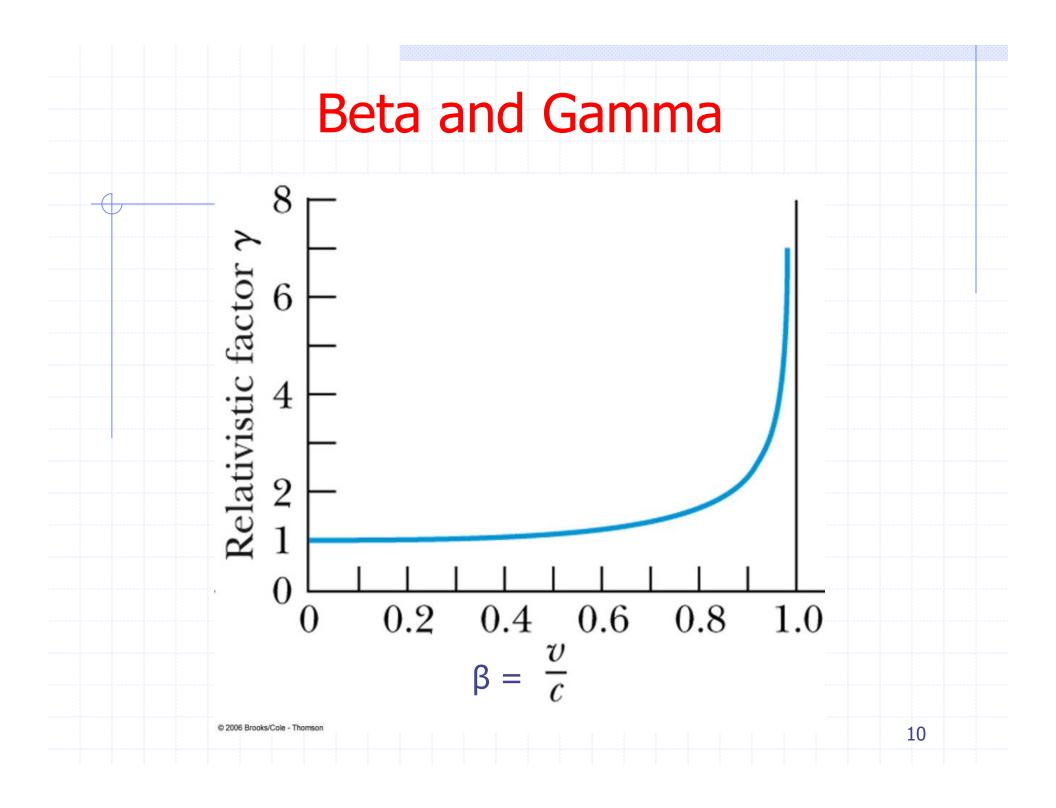
Clock synchronization revisited

Consider two clocks synchronized in S'. Clock B' at x₂ and clock A' at x₁. What times do they read at time t₀ in S?

$$t'_{B} = \gamma \left(t_{0} - \frac{x_{2}V}{c^{2}} \right)$$
$$t'_{A} = \gamma \left(t_{0} - \frac{x_{1}V}{c^{2}} \right)$$

$$t'_{B} - t'_{A} = -\gamma (x_{2} - x_{1}) \frac{V}{c^{2}} = -(x'_{2} - x'_{1}) \frac{V}{c^{2}} = -\frac{L_{0}}{c^{2}}$$

Agrees with results from the homework



Invariants

Invariant quantities have the same value in all inertial frames

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In the next homework, you'll show

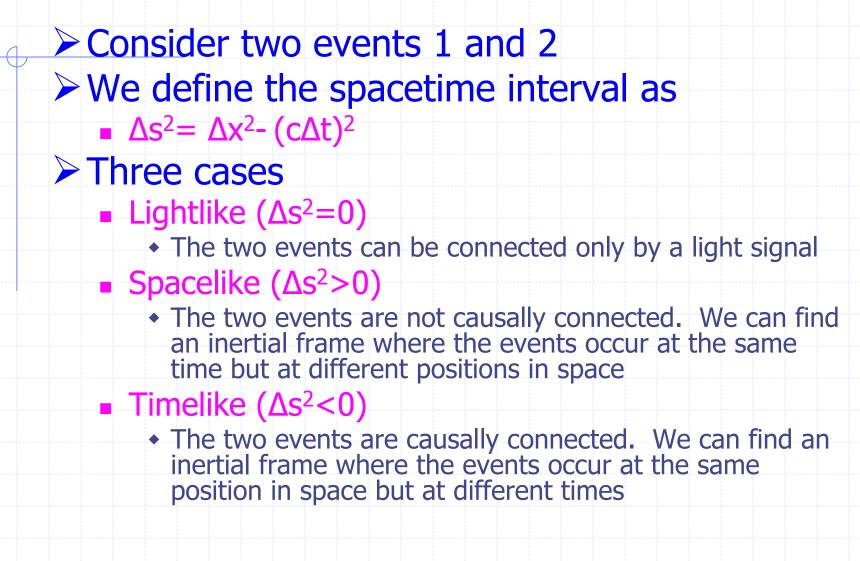
$$s^{2} = x^{2} + y^{2} + z^{2} - (ct)^{2}$$

 $s^2 = s'^2$

$$s'^{2} = x'^{2} + y'^{2} + z'^{2} - (ct')^{2}$$

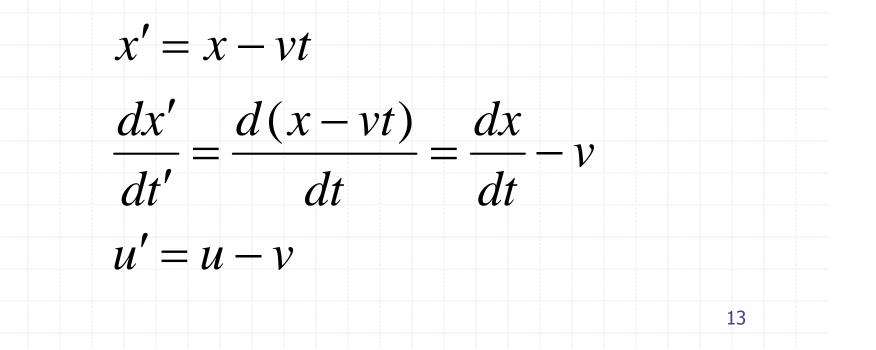
s² is the same for all inertial frames

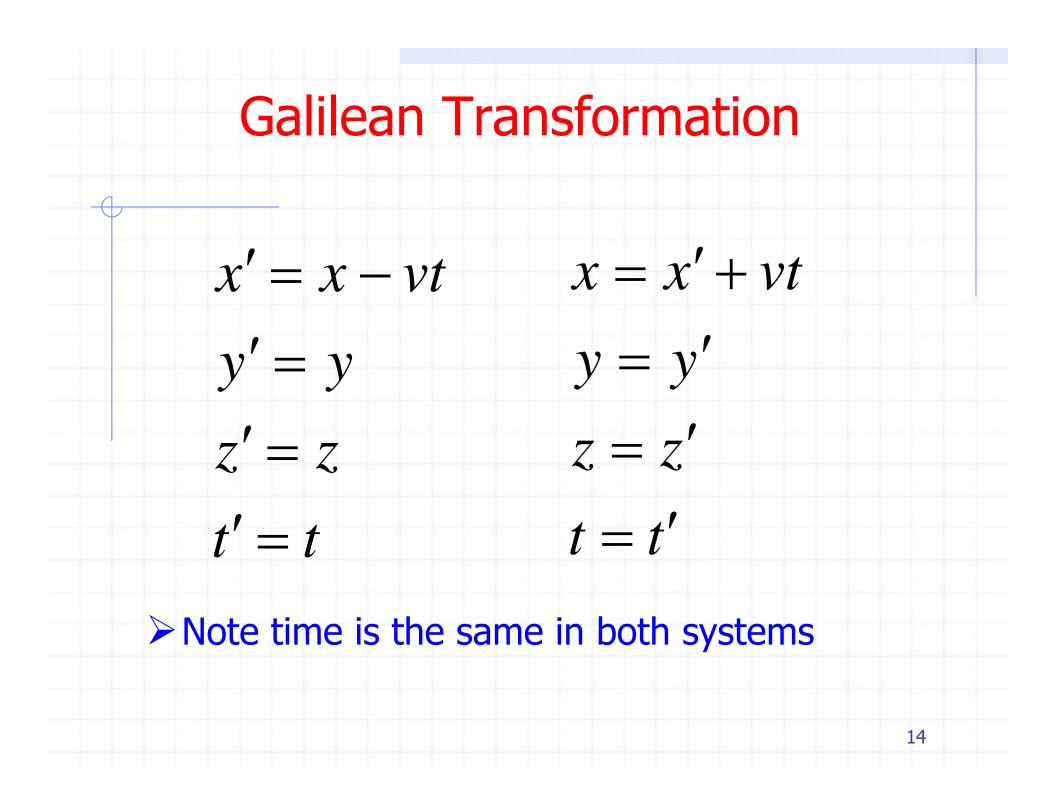
Invariants

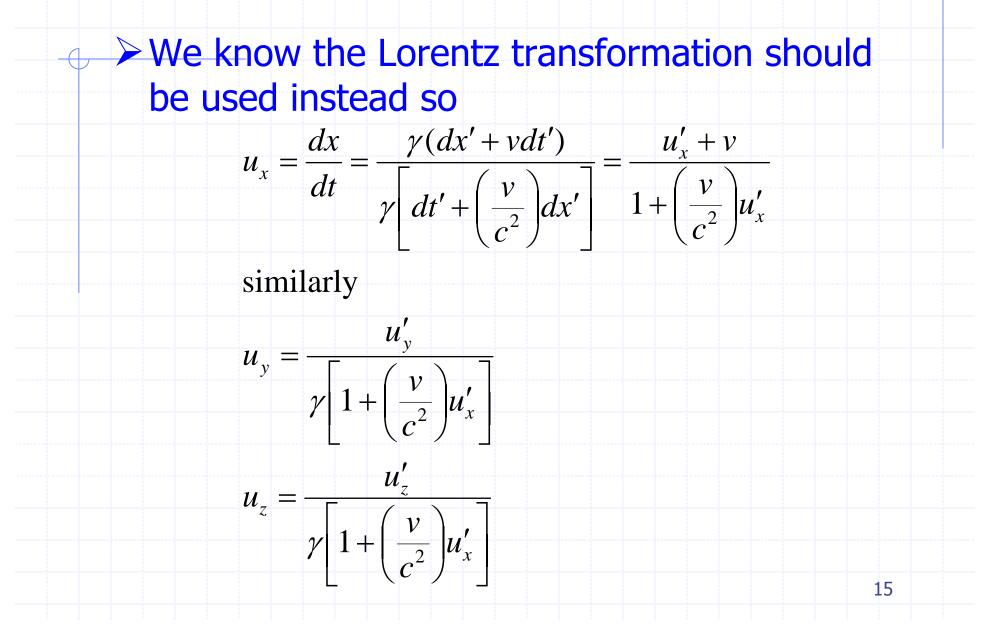


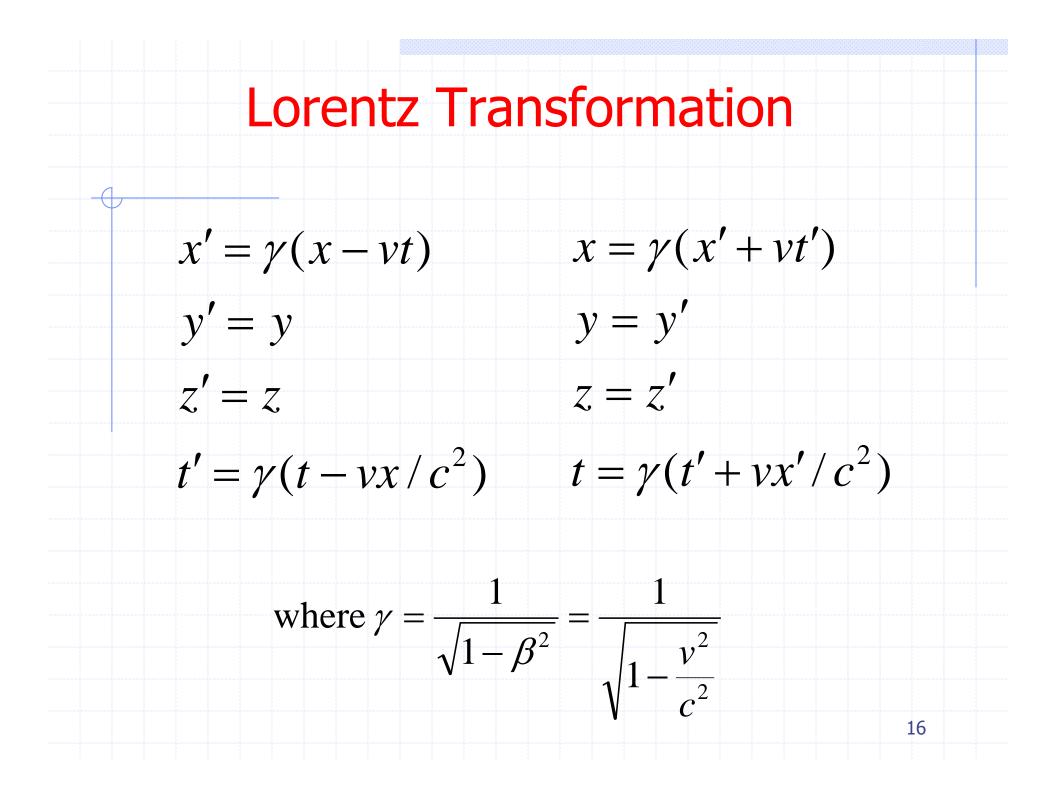
Recall the Galilean transformation between two frames K and K' where K' moves with velocity v with respect to K

Consider an object moving with velocity u in K and u in K'

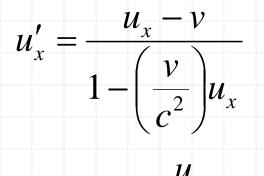


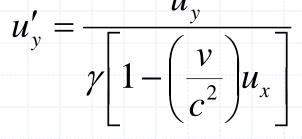


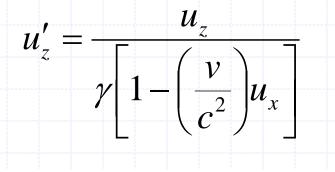




Swapping primed and unprimed variables and letting v go to -v









 \rightarrow Example - let $u'_x = c$, $u'_y = 0$, $u'_z = 0$

$$u_{x} = \frac{(c+V)}{\left(1 + \frac{cV}{c^{2}}\right)} = c, u_{y} = 0, u_{z} = 0$$

Example - *let
$$u'_x=0, u'_y=c, u'_z=0$$*

$$u_x = V, \ u_y = -\frac{c}{\gamma}, \ u_z = 0$$

$$\tan \theta = \frac{u_x}{u} = \frac{\gamma V}{c}$$

A rocket blasts off from the earth at v = 0.90c> A second rocket follows in the same direction at velocity 0.98c >What is the relative velocity of the rockets using a Galilean transformation >What is the relative velocity of the rockets using a Lorentz transformation?

Last time we argued that

$$y = y'$$
 and $z = z'$

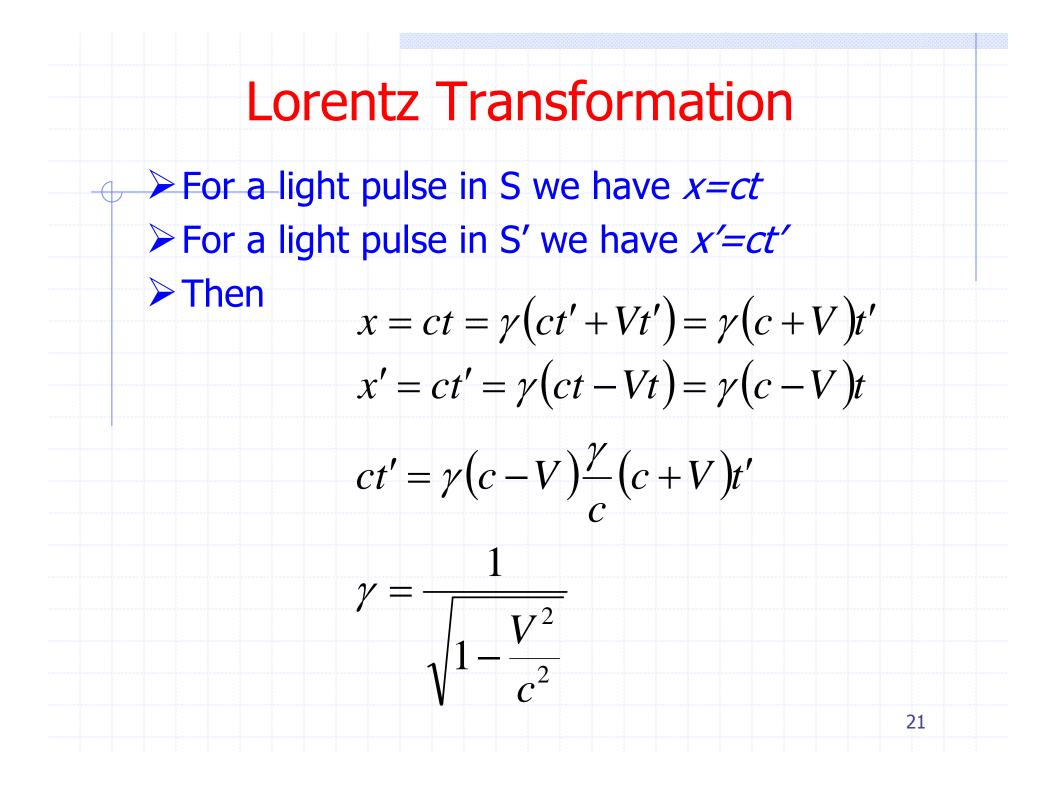
The most general linear transformation for x=f(x',t') is (α, α)

$$x = \gamma x' + \alpha t' = \gamma \left[x' + \frac{\alpha}{x'} t' \right]$$

At low velocities, $\gamma \rightarrow 1$ and $\alpha/\gamma \rightarrow V$ $x = \gamma(x' + Vt')$

The inverse transformation is the same except for the sign of relative motion

$$x' = \gamma (x - Vt)$$



\leftarrow **>** For the *t* transformation

